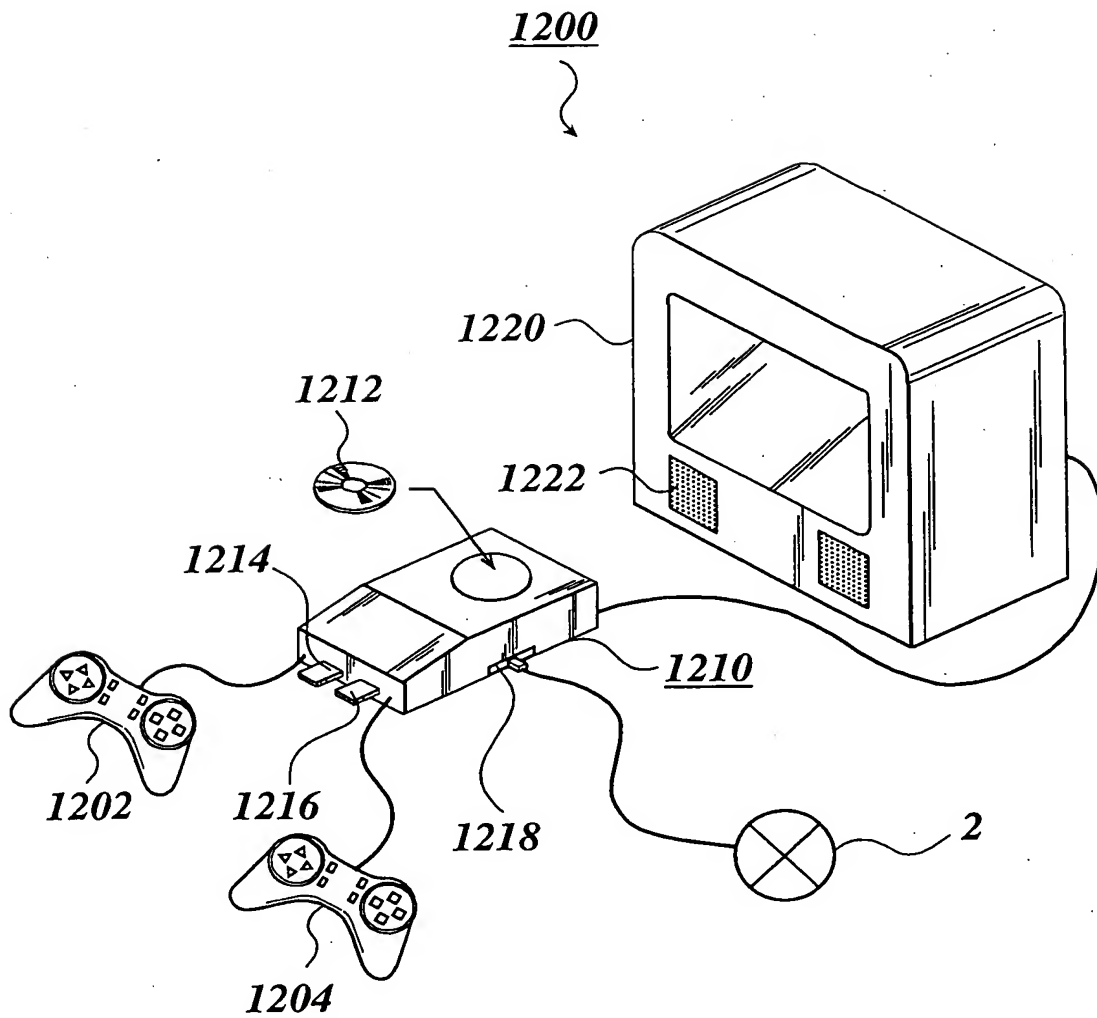
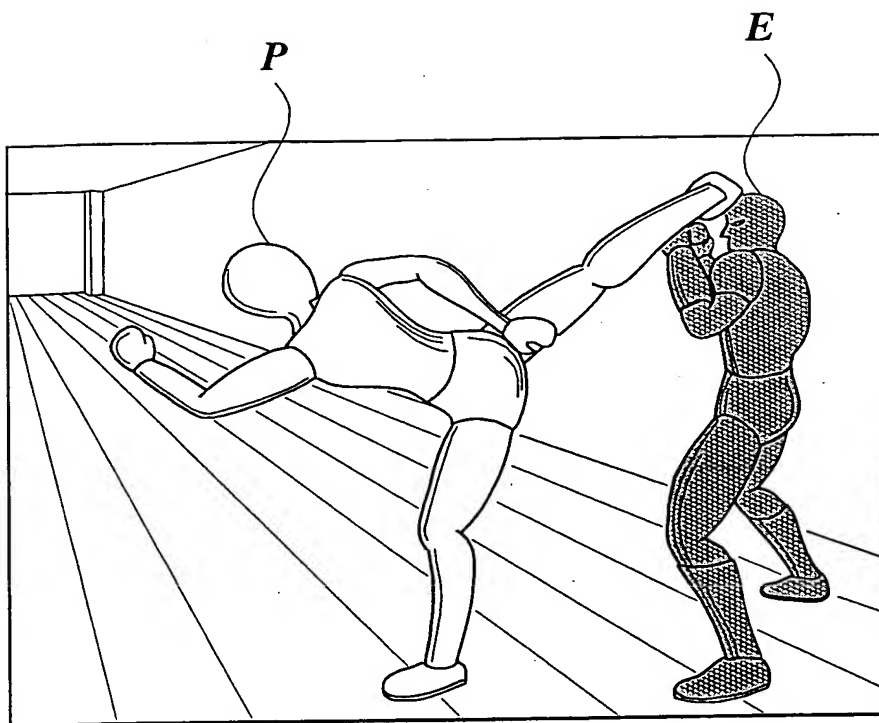


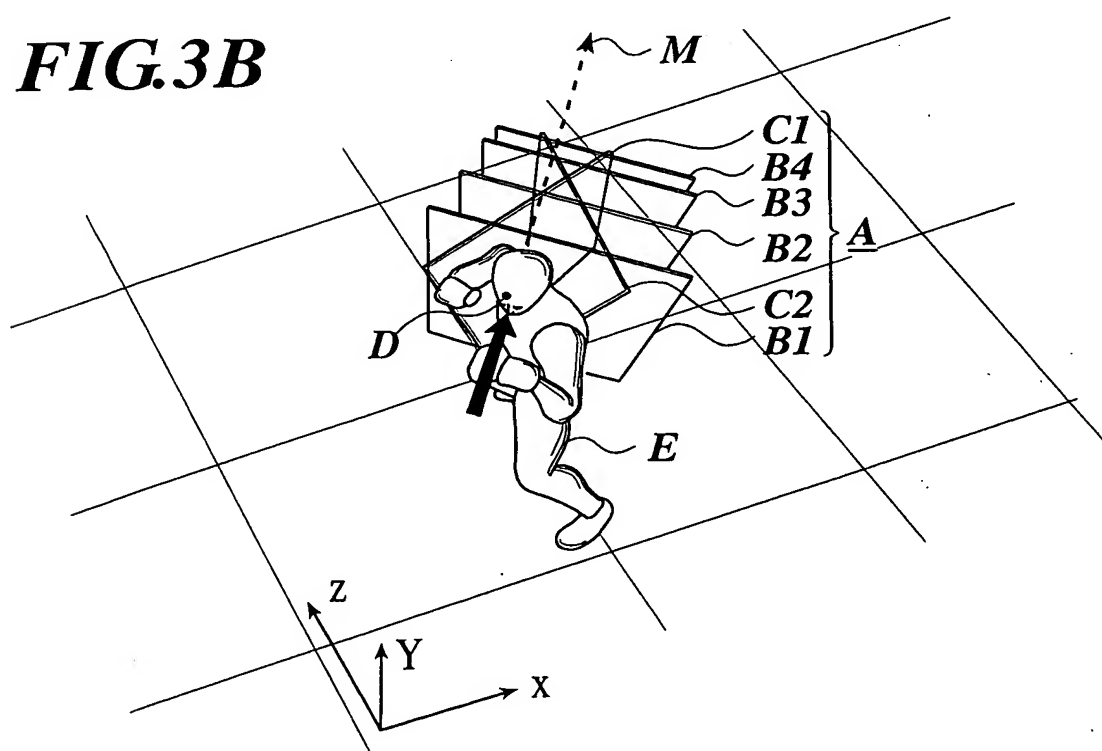
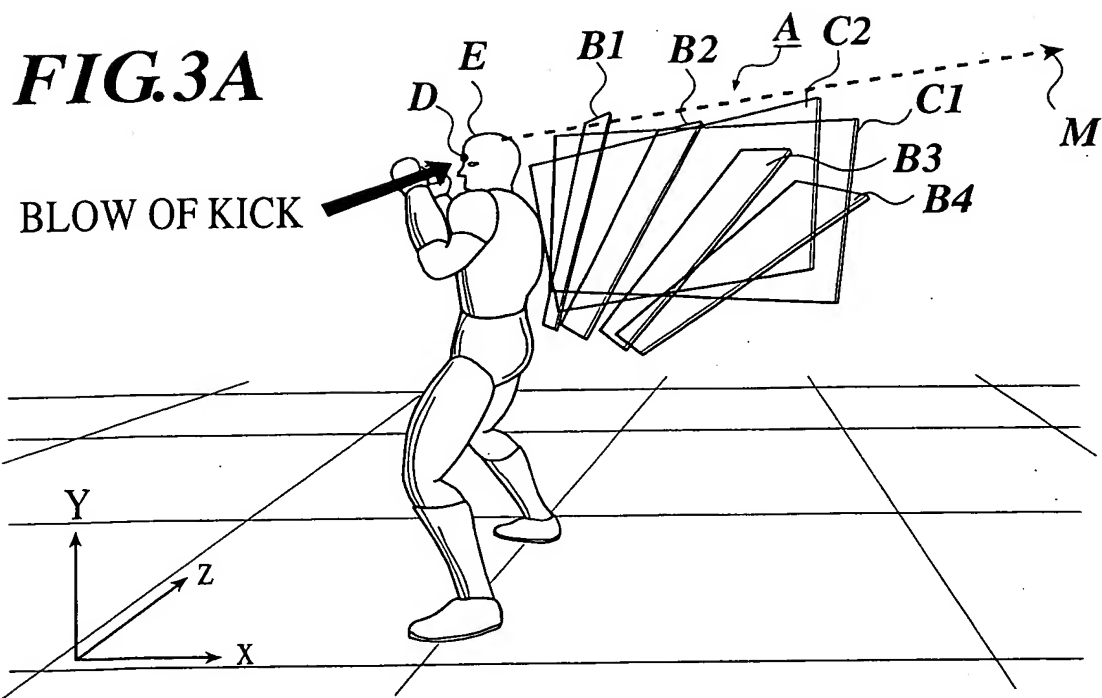


1 / 16
FIG.1



2/ 16
FIG.2





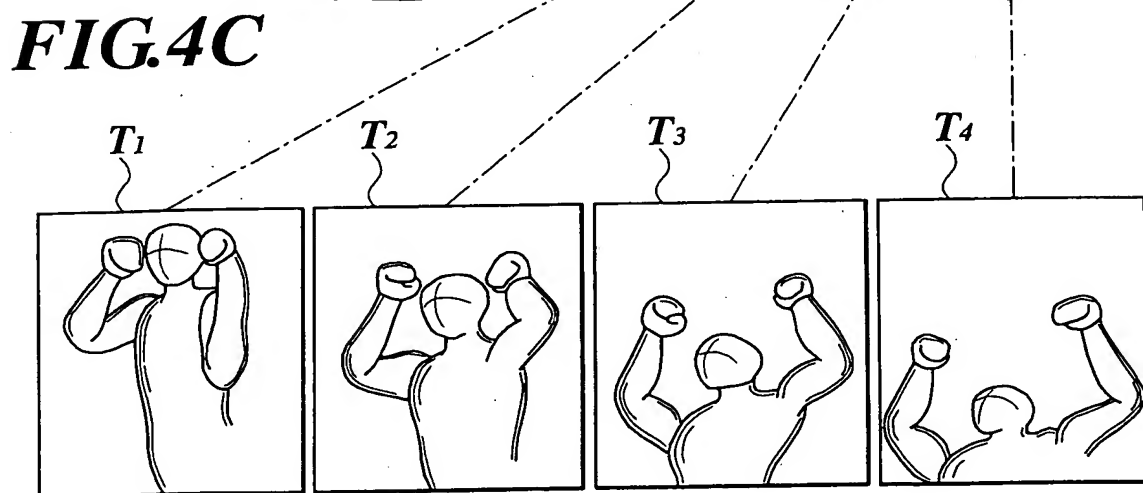
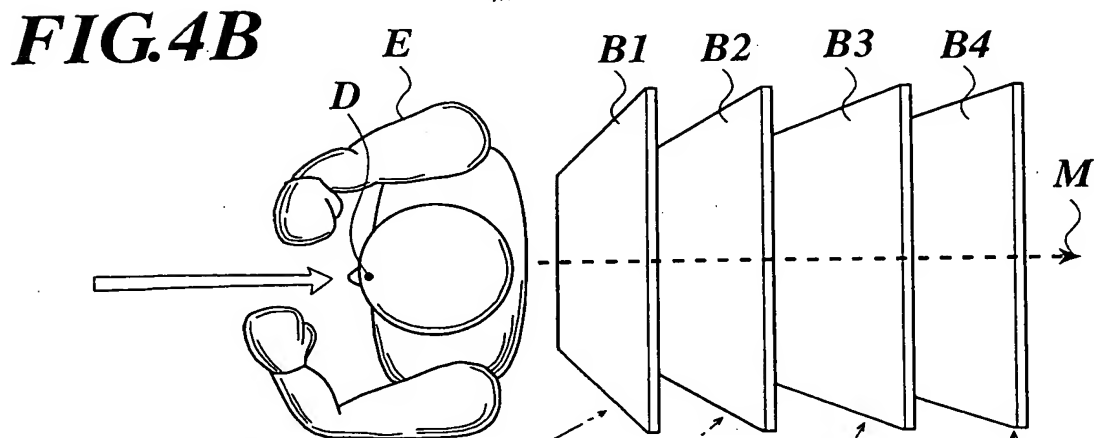
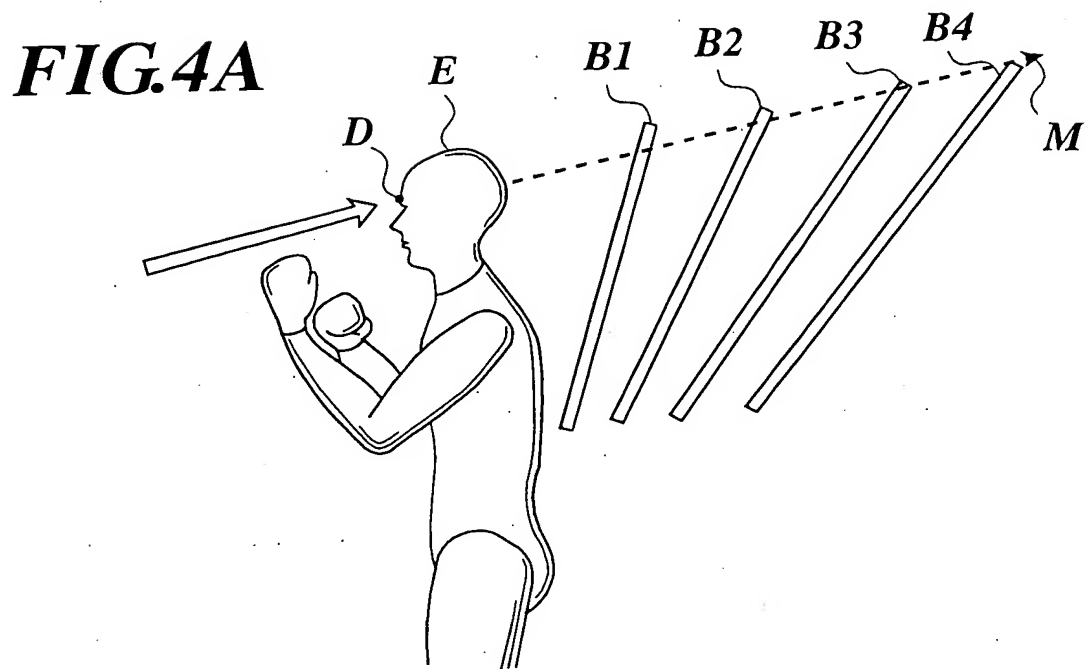


FIG.5A

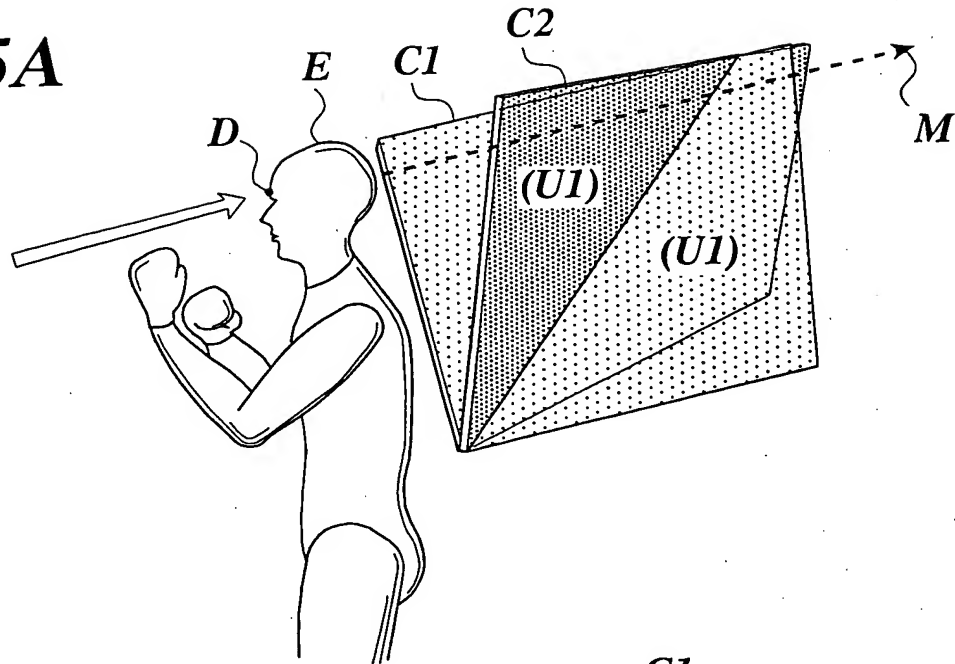


FIG.5B

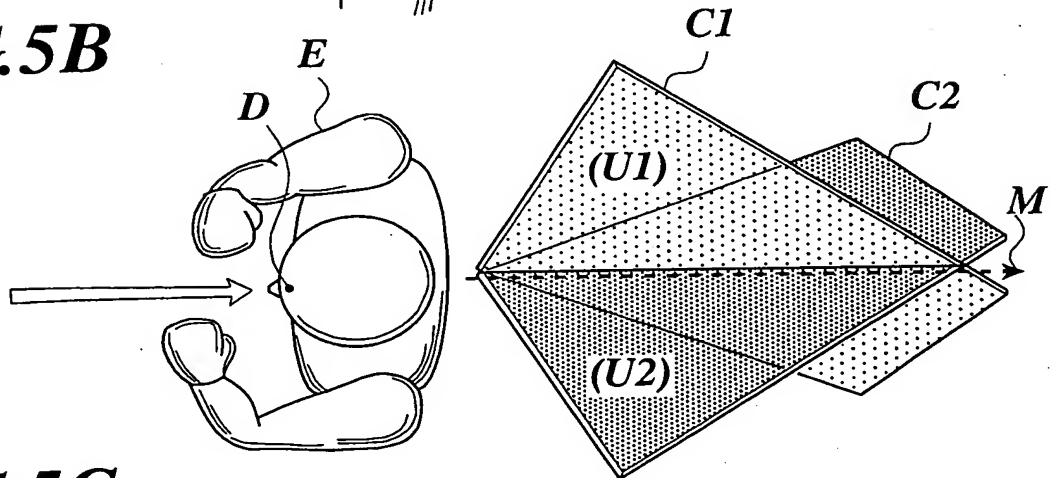


FIG.5C

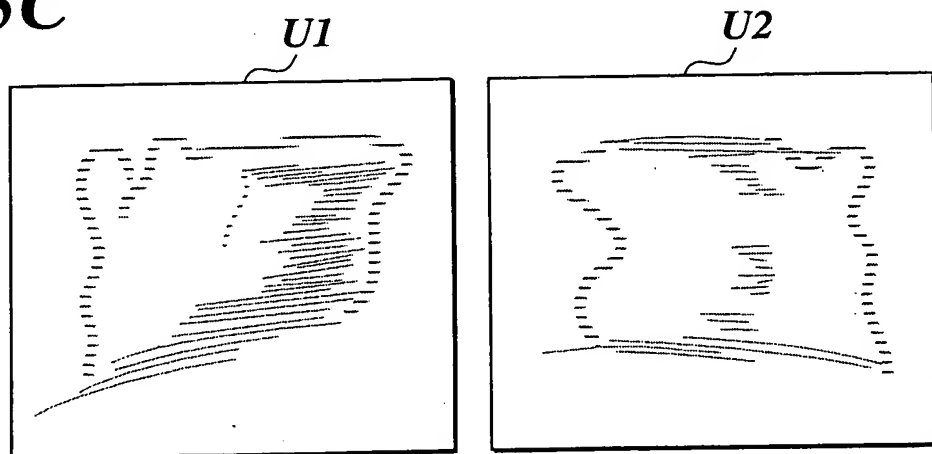


FIG.6A

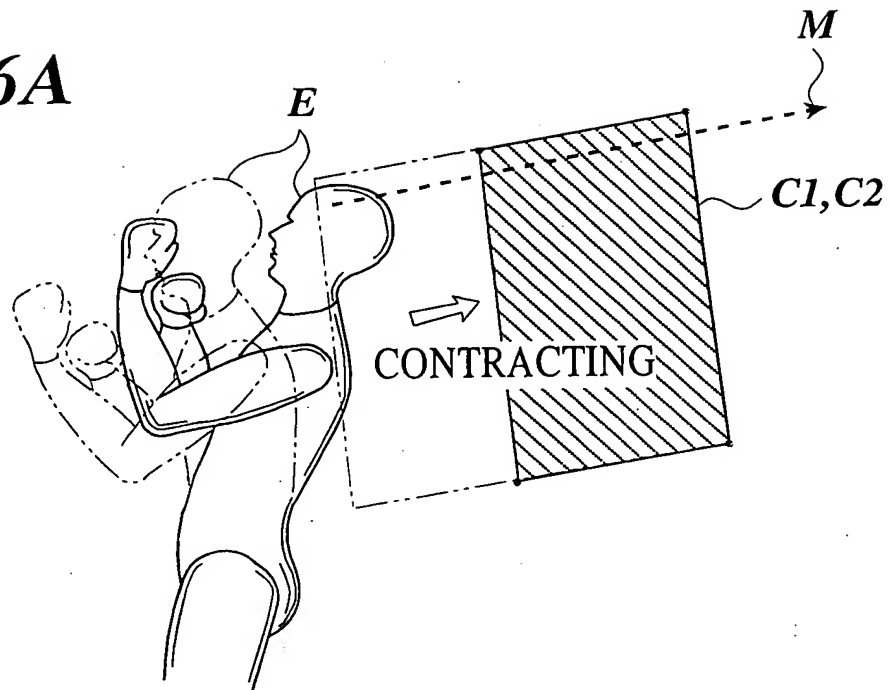


FIG.6B

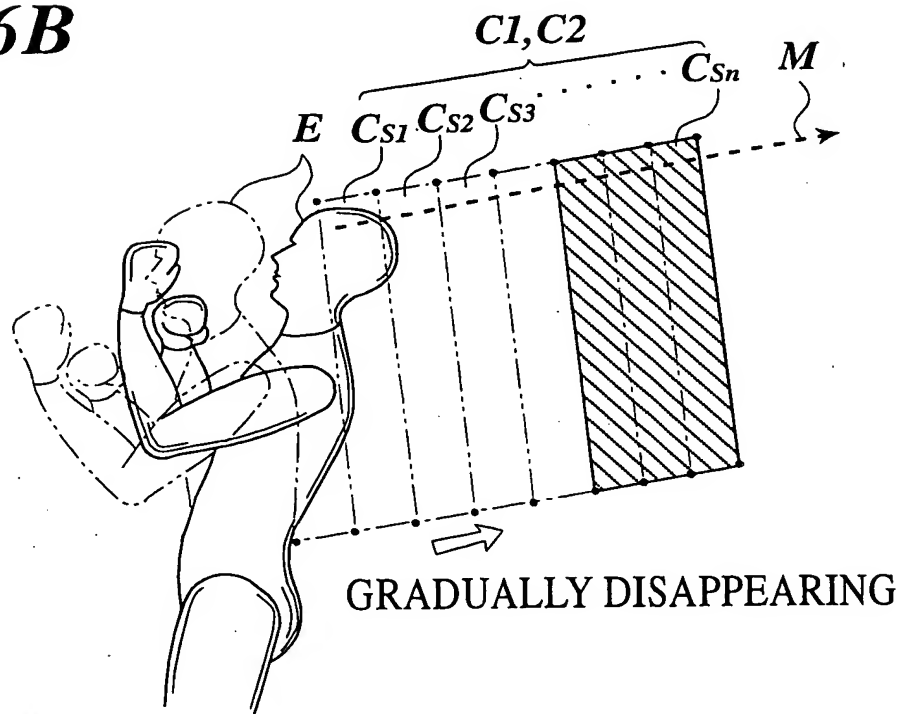


FIG.7A

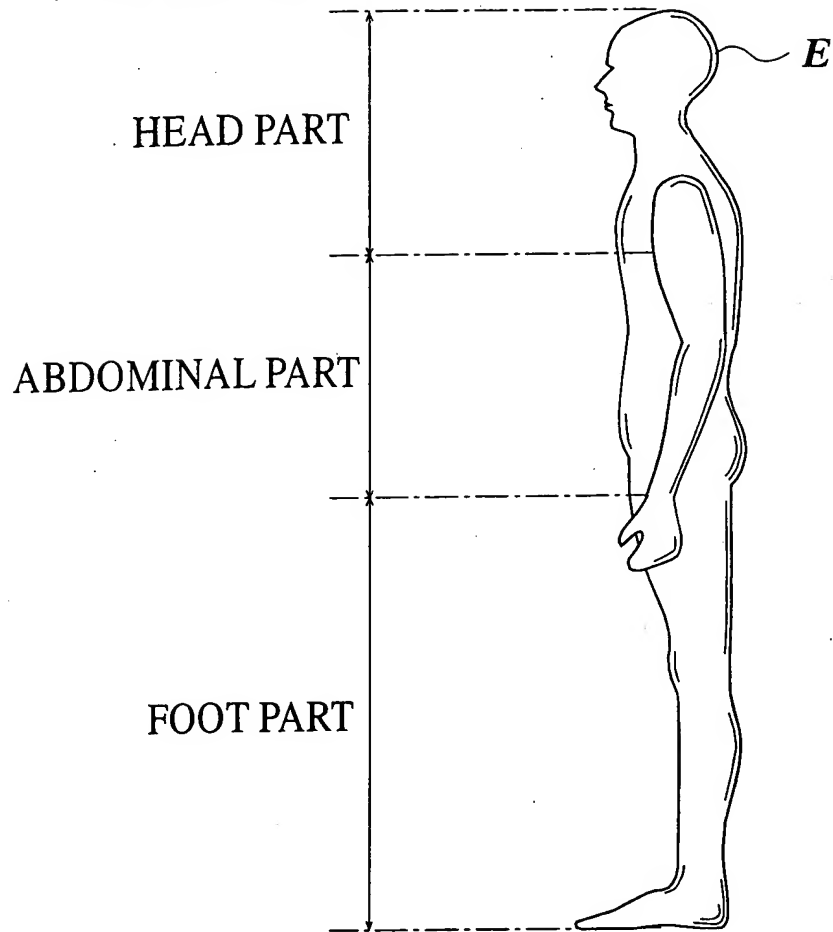
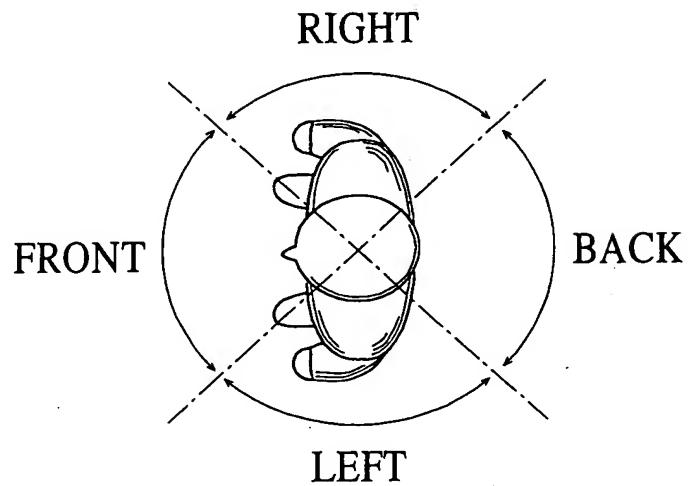
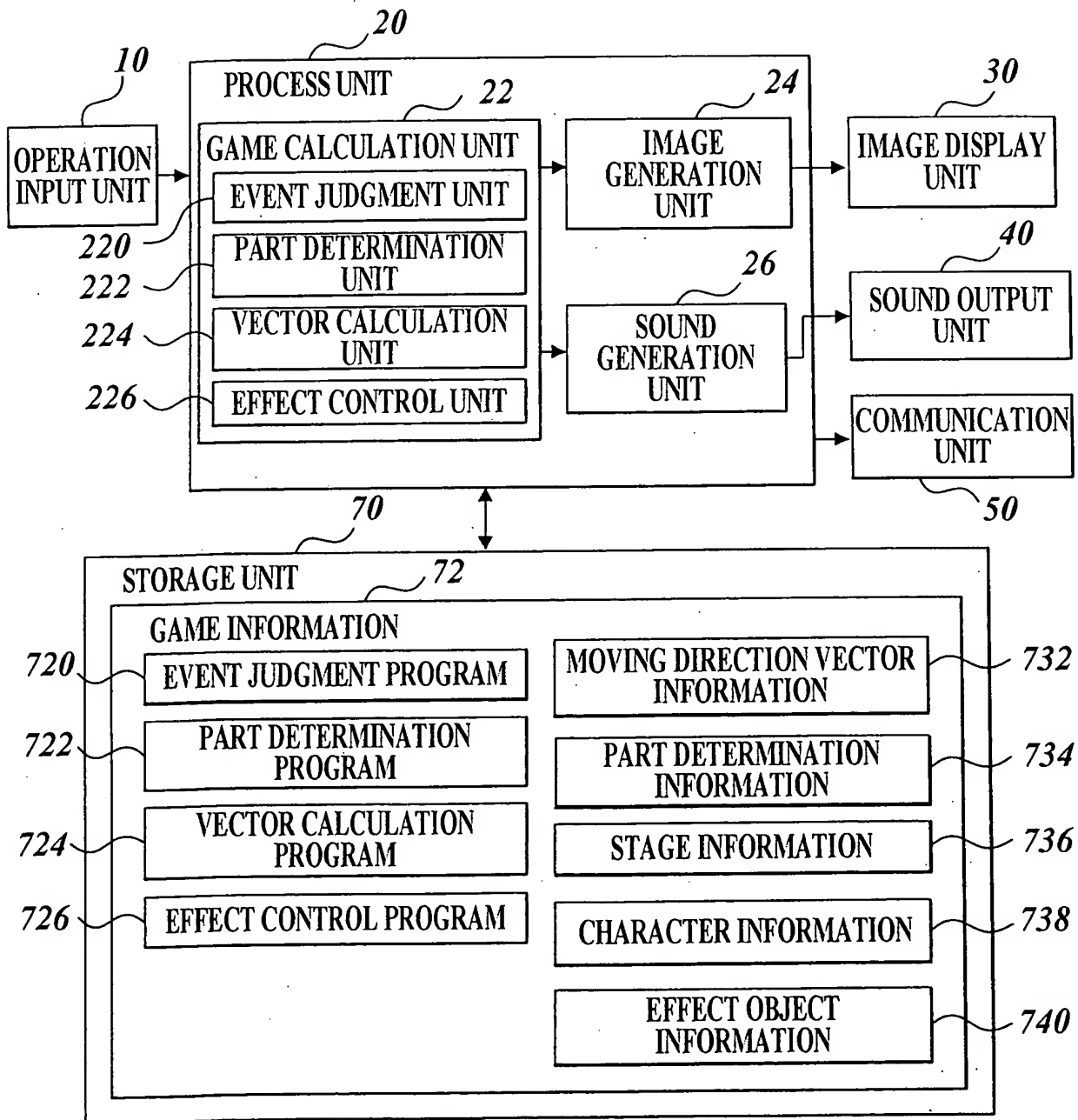


FIG.7B



8 / 16
FIG. 8








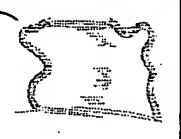
9 / 16
FIG. 9

734

| PART DETERMINATION INFORMATION | | | |
|--------------------------------|--|-----------------------------|--------------|
| 734D | <table><tr><td>CHARACTER ID</td><td>FIGHTER 01</td></tr></table> | CHARACTER ID | FIGHTER 01 |
| CHARACTER ID | FIGHTER 01 | | |
| 734E | <table><tr><td>HITTING POINT COORDINATE</td><td>(Xd, Yd ,Zd)</td></tr></table> | HITTING POINT COORDINATE | (Xd, Yd ,Zd) |
| HITTING POINT COORDINATE | (Xd, Yd ,Zd) | | |
| 734F | <table><tr><td>DETERMINED PART</td><td>1(HEAD PART)</td></tr></table> | DETERMINED PART | 1(HEAD PART) |
| DETERMINED PART | 1(HEAD PART) | | |
| 734G | <table><tr><td>HIT DIRECTION</td><td>1(FRONT)</td></tr></table> | HIT DIRECTION | 1(FRONT) |
| HIT DIRECTION | 1(FRONT) | | |

10 / 16
FIG.10

740

| EFFECT OBJECT INFORMATION | | | | 740a |
|---------------------------|--|---|------------|------|
| CHARACTER ID | FIGHTER 01 | | | 740b |
| DETERMINED PART | 1(HEAD PART) | | | 740c |
| HIT DIRECTION | 1(FRONT) | | | |
| | 740d | 740e | 740f | |
| FIRST EFFECT Obj | APPEARANCE IMAGE | POSITIONAL INFORMATION | MODEL DATA | |
| B1 | T_1  | (X_1, Y_1, Z_1) $(\theta_1, \theta_1, \theta_1)$ | model-111a | |
| B2 | T_2  | (X_2, Y_2, Z_2) $(\theta_2, \theta_2, \theta_2)$ | model-111a | |
| B3 | T_3  | (X_3, Y_3, Z_3) $(\theta_3, \theta_3, \theta_3)$ | model-111a | |
| B4 | T_4  | (X_4, Y_4, Z_4) $(\theta_4, \theta_4, \theta_4)$ | model-111a | |
| | 740d | 740e | 740f | |
| FIRST EFFECT Obj | APPEARANCE IMAGE | POSITIONAL INFORMATION | MODEL DATA | |
| C1 | $U1$  | (X_5, Y_5, Z_5) $(\theta_5, \theta_5, \theta_5)$ | model-111b | |
| C2 | $U2$  | (X_6, Y_6, Z_6) $(\theta_6, \theta_6, \theta_6)$ | model-111b | |

11 / 16
FIG. 11

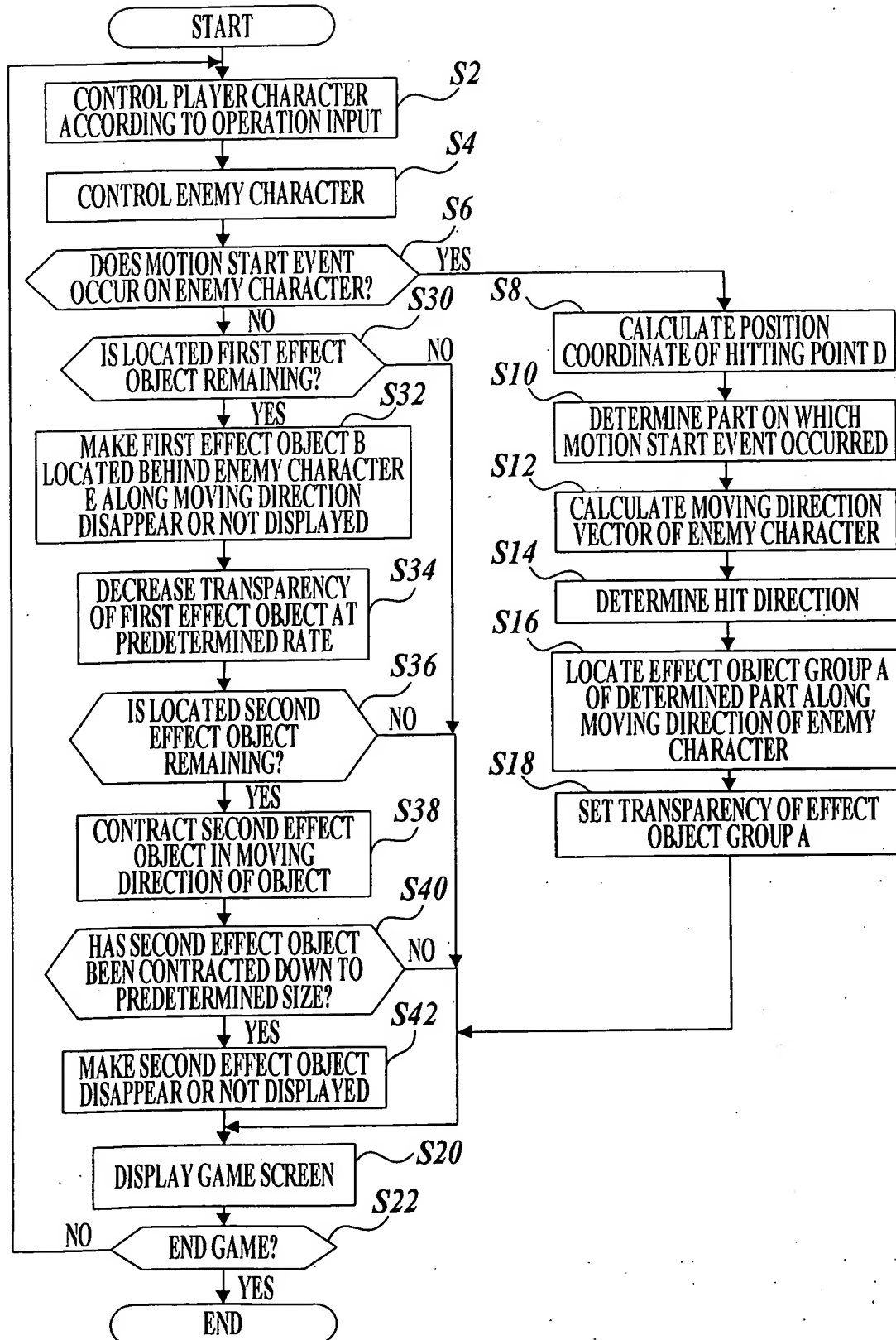


FIG.12A

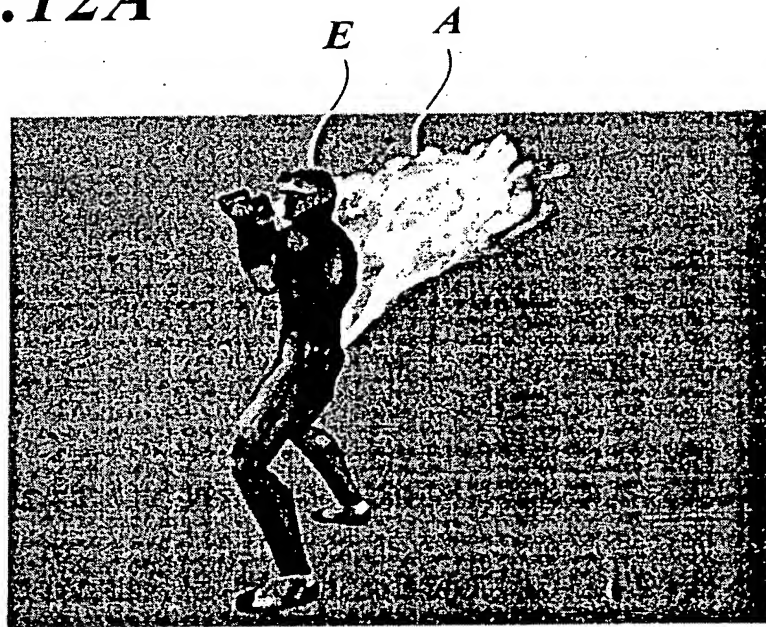


FIG.12B

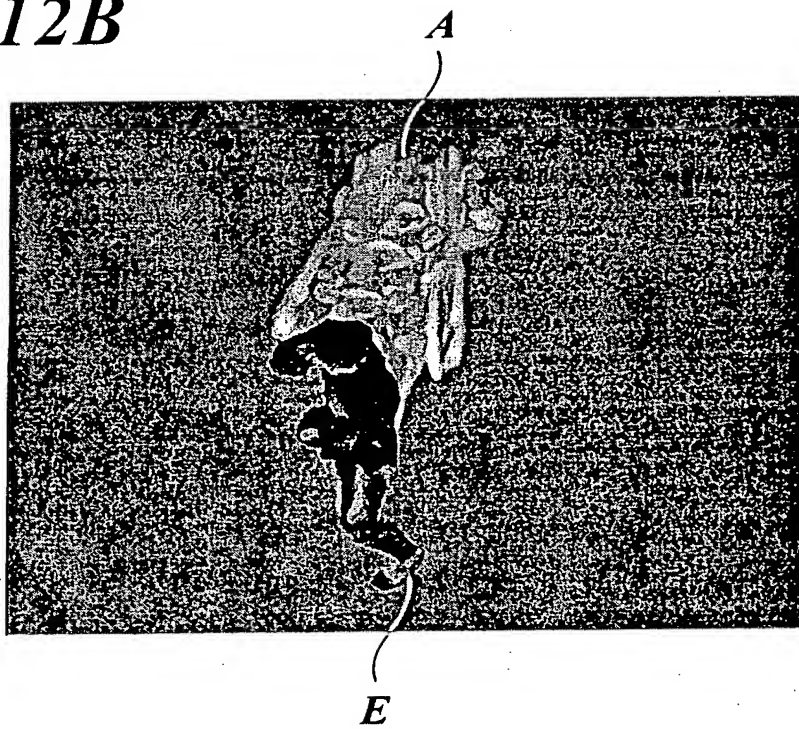
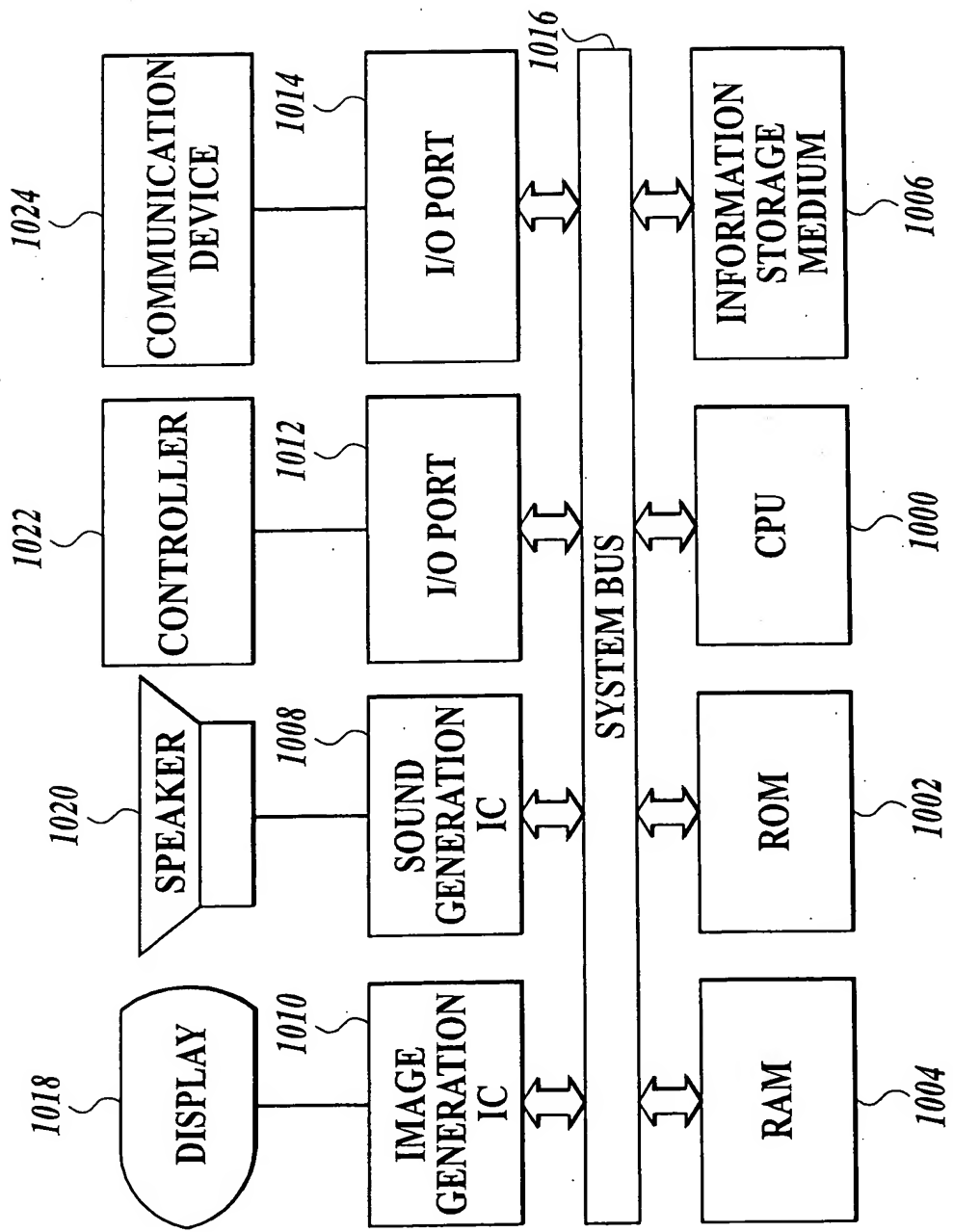


FIG.13



14/16
FIG. 14

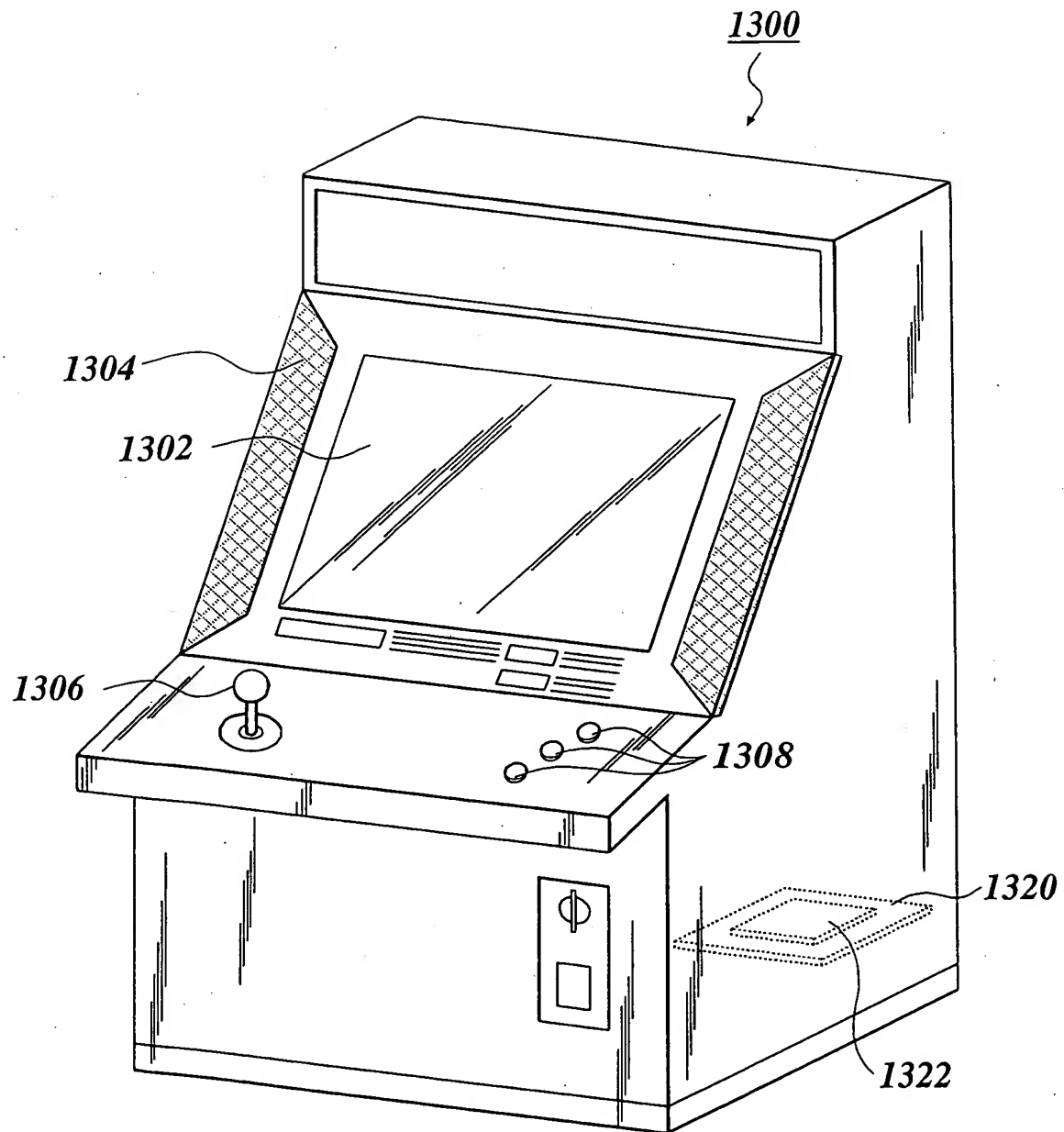


FIG.15A

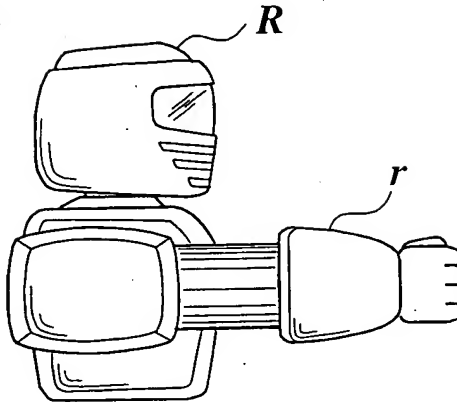


FIG.15B

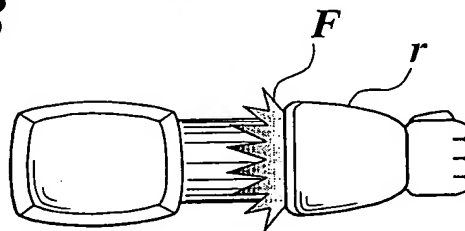


FIG.15C

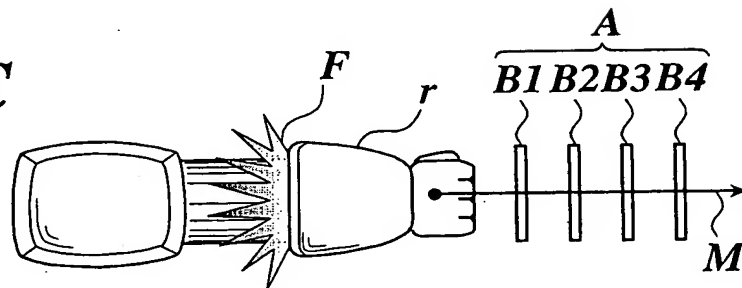


FIG.15D

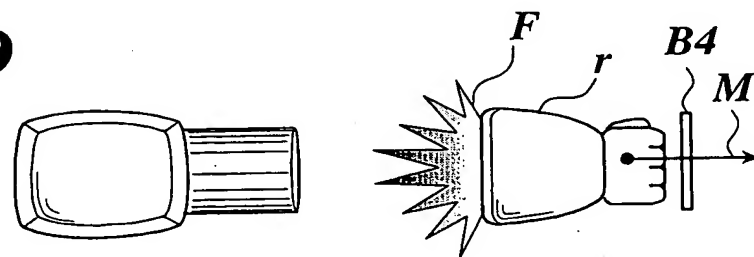


FIG.16A

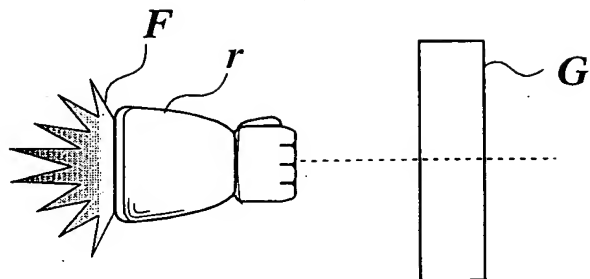


FIG.16B

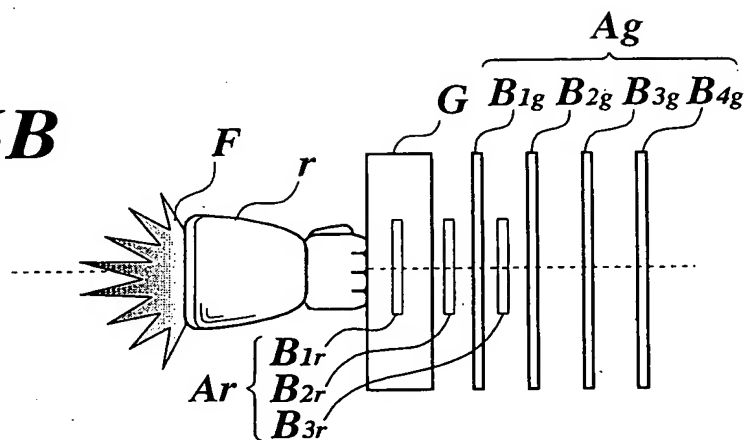


FIG.16C

